



# DyNaLab Test Bench

WIND ASSURING CONFIDENCE  
THROUGH COMPETENCE

Torben Jersch

3rd Annual International Workshop on  
GRID SIMULATOR TESTING  
OF  
ENERGY SYSTEMS AND WIND TURBINE POWERTRAINS

November 5-6, 2015 - Tallahassee, Florida, USA





## Short profile of Fraunhofer IWES North-West

Managing Director:

Prof. Dr.-Ing. Andreas Reuter

Research spectrum:

Wind energy from material development to grid connection

Operational budget 2014:

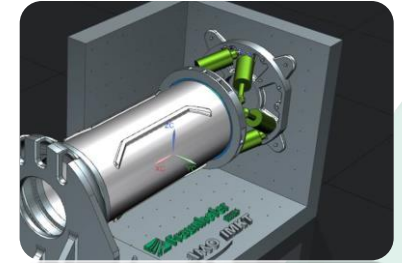
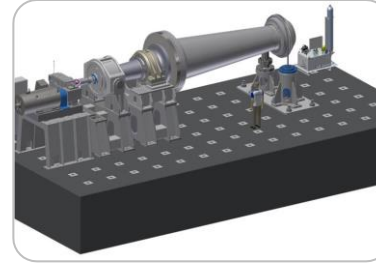
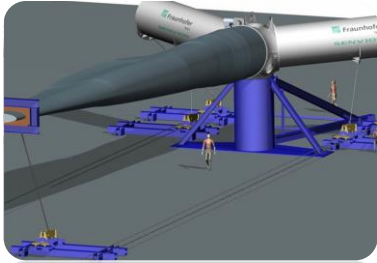
around 13,2 million €

Staff:

150 employees

Previous investments in the establishment of the institute: € 60 million

Strategic Association with ForWind and the German Aerospace Center (DLR)



## Short profile of Division Wind Turbine and System Technology

Division Manager:

Prof. Dr.-Ing. Jan Wenske

Research spectrum:

Structural durability, mechatronics,  
power electronics and control  
in the area of entire wind turbines  
Large scale test benches for mechanics,  
electronics and Power mechatronics

Staff:

30 employees

Division locations:

Bremerhaven – Hannover



# Planning in 2013

## Wind Load Simulation 6-DOF:

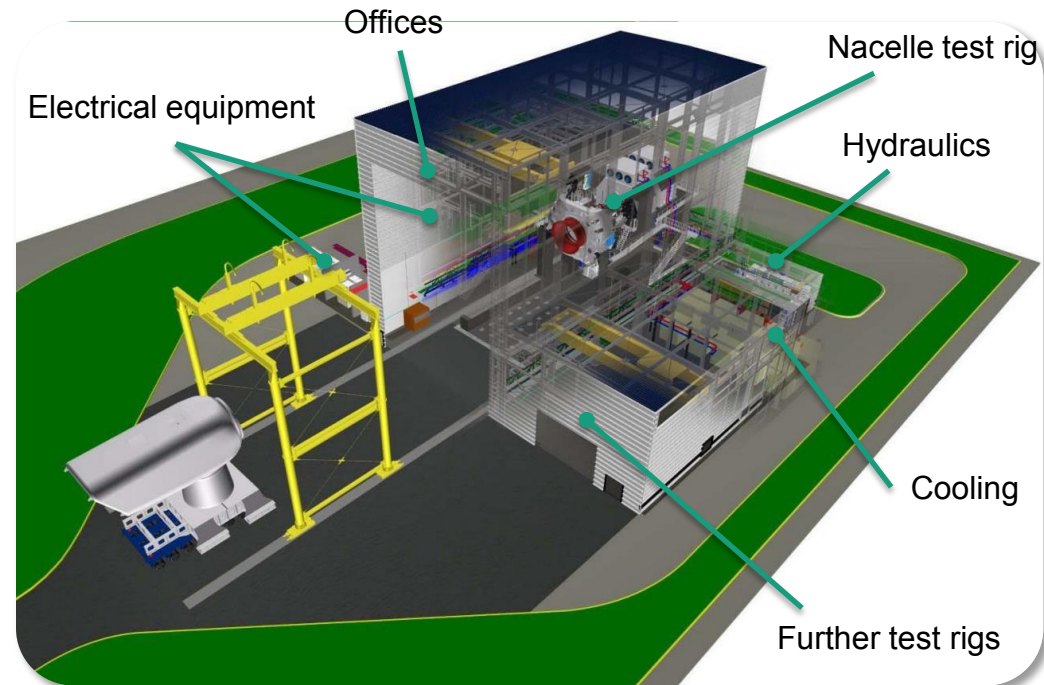
- ↘ Bending:  $\pm 20000 \text{ kNm}$
- ↘ Torque:  $8600 \text{ kNm}$
- ↘ Motor speed:  $\pm 25 \text{ rpm}$

## Grid load simulation:

- ↘ LVRT & HVRT
- ↘ Low THD level ( $< 2\%$ )

## Auxiliaries:

- ↘ Offices for 24 researchers / technicians
- ↘ 1.5 MW installed hydraulic power
- ↘ 3.5 MW installed cooling power
- ↘ 9.0 MVA grid connection @ 20 kV





# 10MW Full Nacelle Test bench



**Design – two ESM on one Shaft - Nominal Power of 10 MW @ 11rpm:**

- Civil and building construction 01/14 – 04/15
- Test bench construction 12/14 - 06/15
- Commissioning 05/15 – 09/15
- Transfer of ownership 10/15

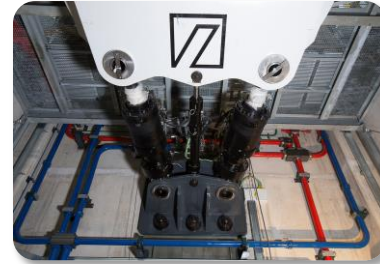
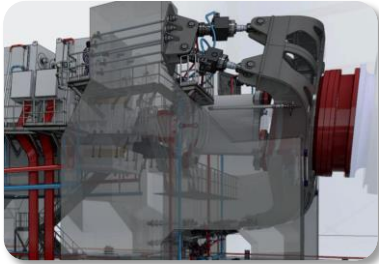
**JPT Testing:**

- Installation of electrical equipment 07/15
- Installation of DUT 08/15

**Opening ceremony 10/15**

**Invest:**

- 32 mio €



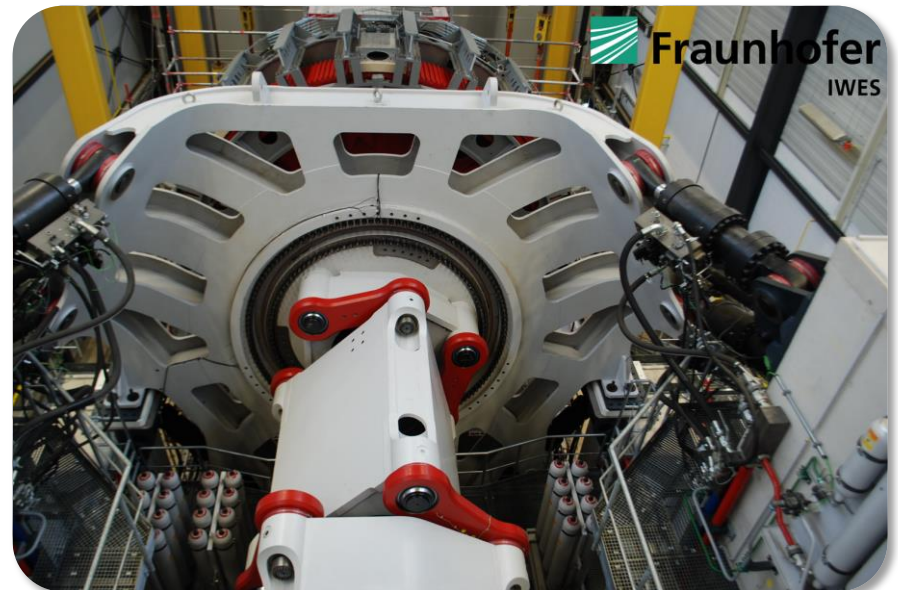
# Load Application System

## Design – three nominal voltage level

- 5 DOF
- Bending moments up to 20MNm
- Dynamic 0-2 Hz
- 0-G Kit + Blocking cylinders
- 1.2 MW Hydraulic power
- Applying realistic load time series

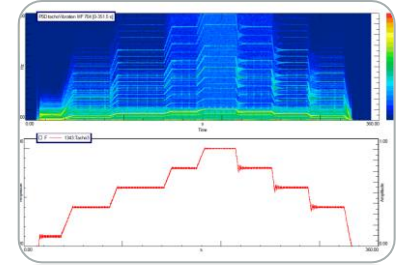
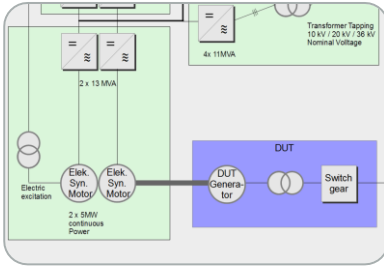
## Commissioning:

- Running in position and force Mode
- Running against blocking cylinders
- Calibration of Load application unit by using load cells



Covering  
Energy  
Losses





# Drivetrain

## Design – two ESM on one Shaft - Nominal Power of 10 MW @ 11rpm

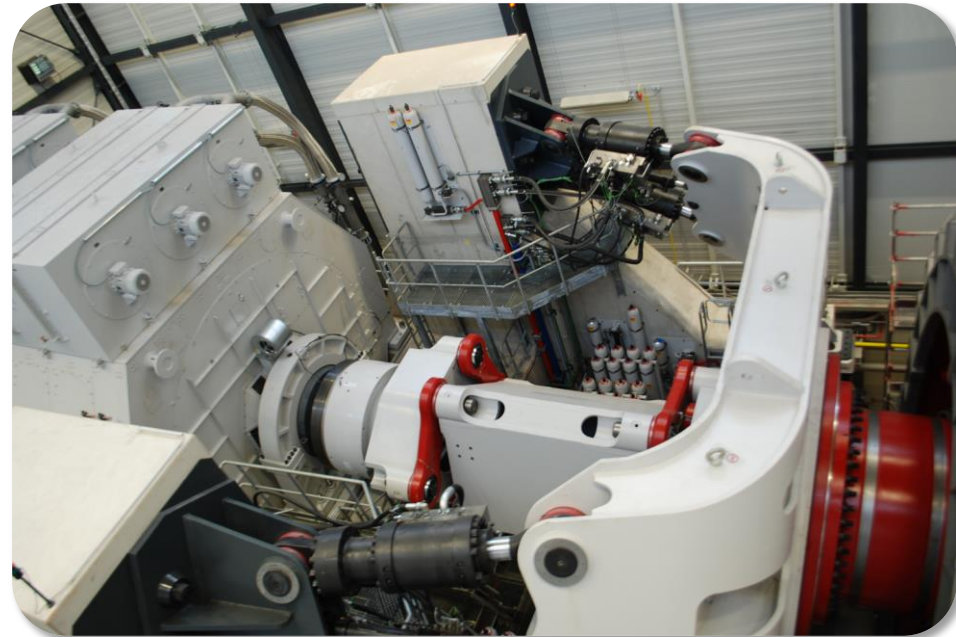
- Torque: S1 8600 kNm – S6 13000 kNm
- Motor speed:  $\pm 25$  rpm
- Inverters: 2 x 13 MVA

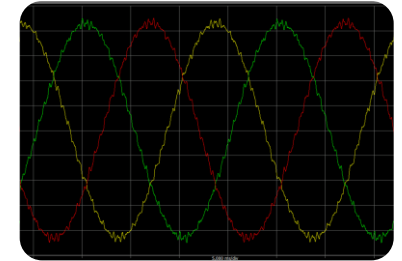
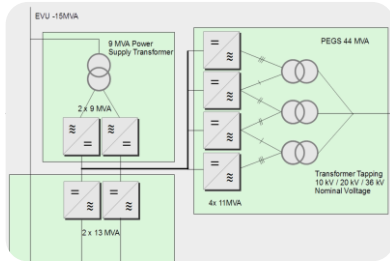
## Commissioning:

- Back-to-Back test at nominal design loads
- Heating test
- Dynamic behavior

## Auxiliaries:

- Real-time control Interface
- Adjustable safety clutch





# Gridsimulator

## Design – three nominal voltage level

- Nominal tapping: 10 kV – 20 kV – 36 kV
- HVRT tapping: 13 kV – 26 kV – 46.8 kV
- LVRT capability: to 0V

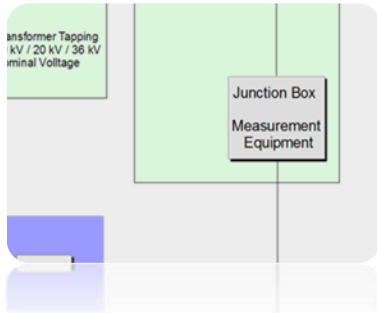
## Commissioning:

- Improvement of PEGS for faster slopes

## Further work:

- Voltage feedback
- Commissioning of ABB <> Opal-RT high speed interface
- Reduction of high harmonics





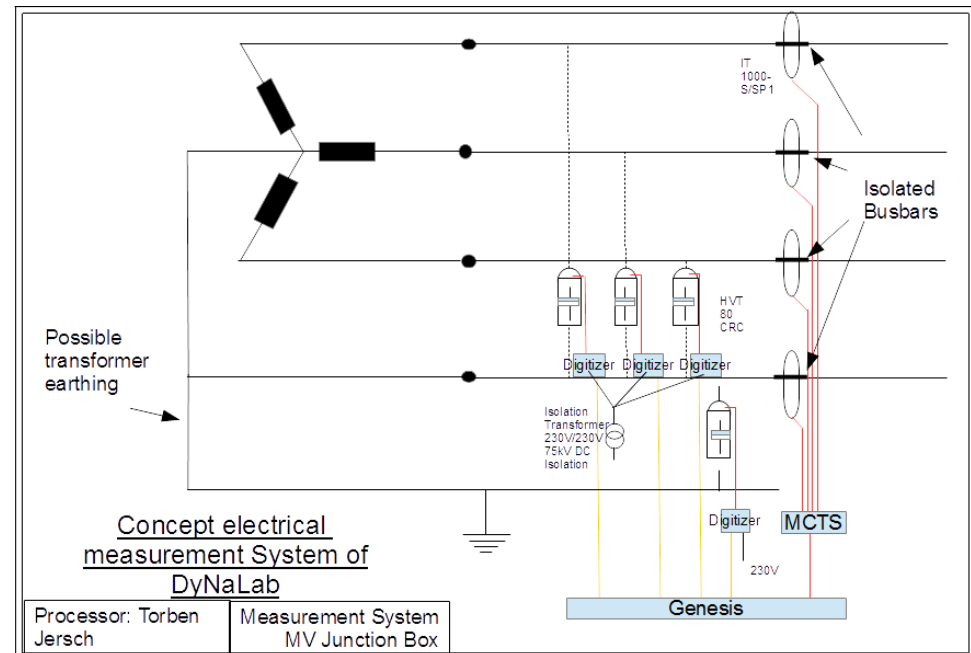
# Electrical Metrology

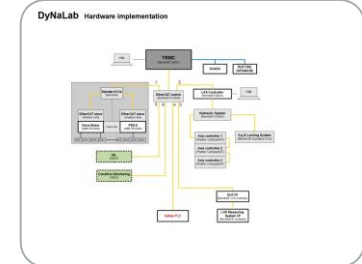
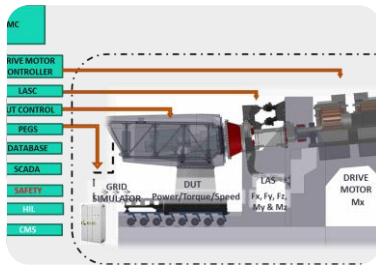
## Electrical metrology

- Synchronized measurements of 50 channels
- Visualization in control rooms
- 4 TByte storage capability
- By GPS clock synchronized measurements
- EtherCat Interface

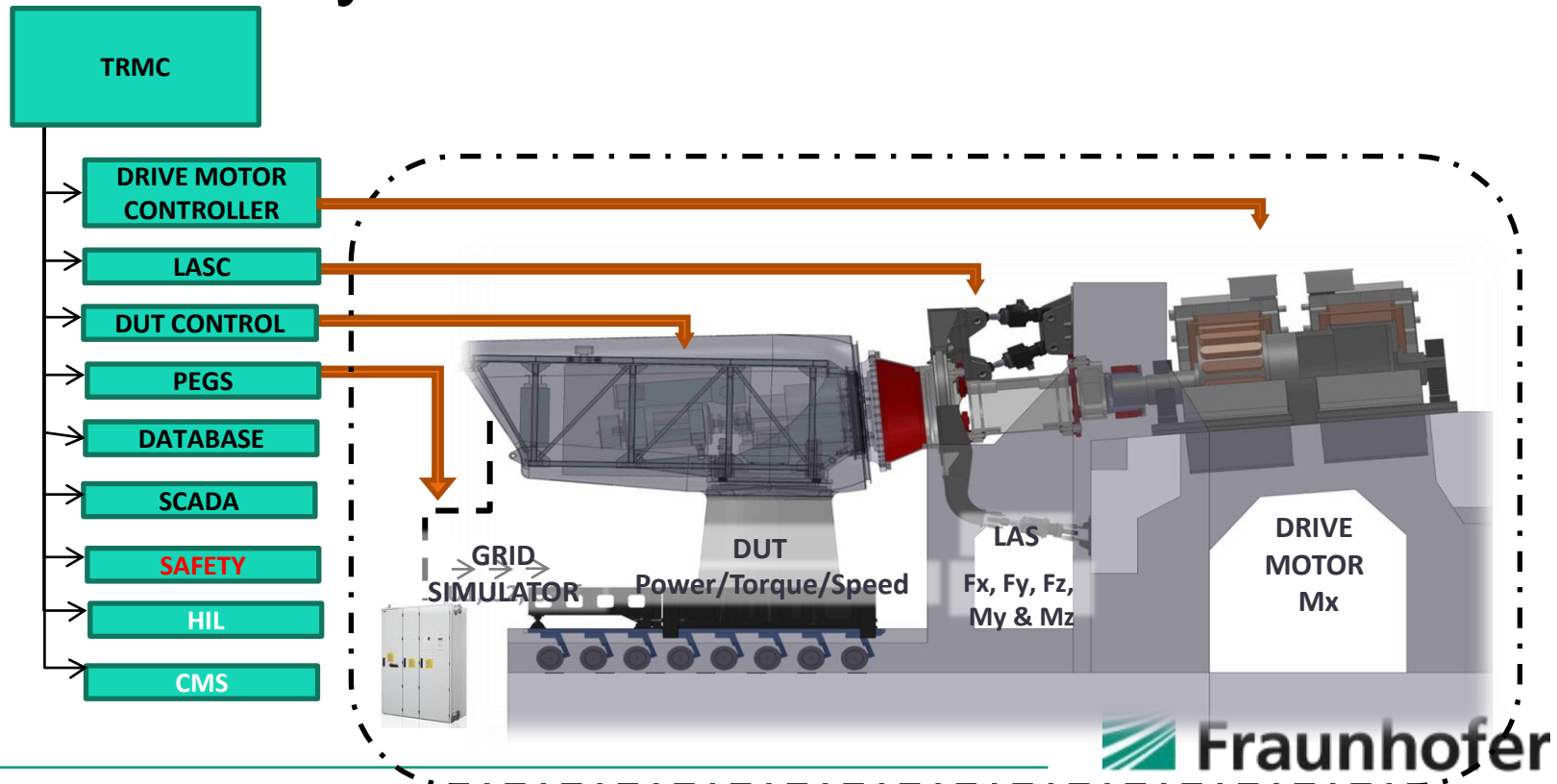
## Design – MV-Measurements

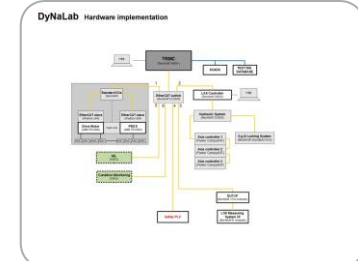
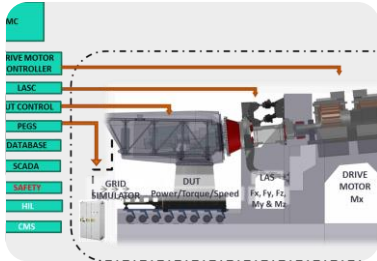
- Designed for in IT-Grid
- Isolated voltage up to 75 kV
- Ultra precise measurements of voltages and currents
- Bandwidth up to 1 MHz





# Control - System





# Control - System

## Real-Time Control

- Real-Time EtherCat Fieldbus
- 2ms – 1ms Cycle time for controlling the main actuators
- Real-time simulation platform for WEC-models (Beckhoff) - grid and power electronics models (Opal-RT) with EtherCat interface
- Time synchronization of all components over distributed clock functionality

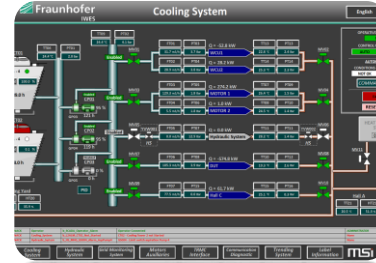
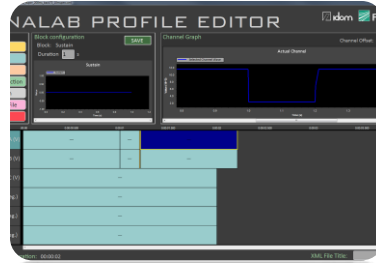
## ABB - Control

- EtherCat interface to ABB
- Advanced control on ABB-Inverters

## Safety System

- Programmable Safety interface
- Safety over EtherCat





# HMI – Graphical User Interface

## Profile Editor

- Defining profiles of set points of LASC, Motor, PEGS

## SCADA

- Control of auxiliaries, Cooling, Hydraulic pumps, Switchgears, Fans
- Supervision of Power consumption, Grid

## HMI – TRMC

- Operating the Test bench

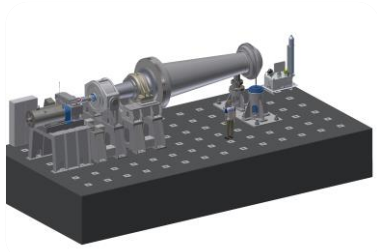
## Communication

- Beckhoff to Labview communication via ADS Interface



# Actual Projects and Outline





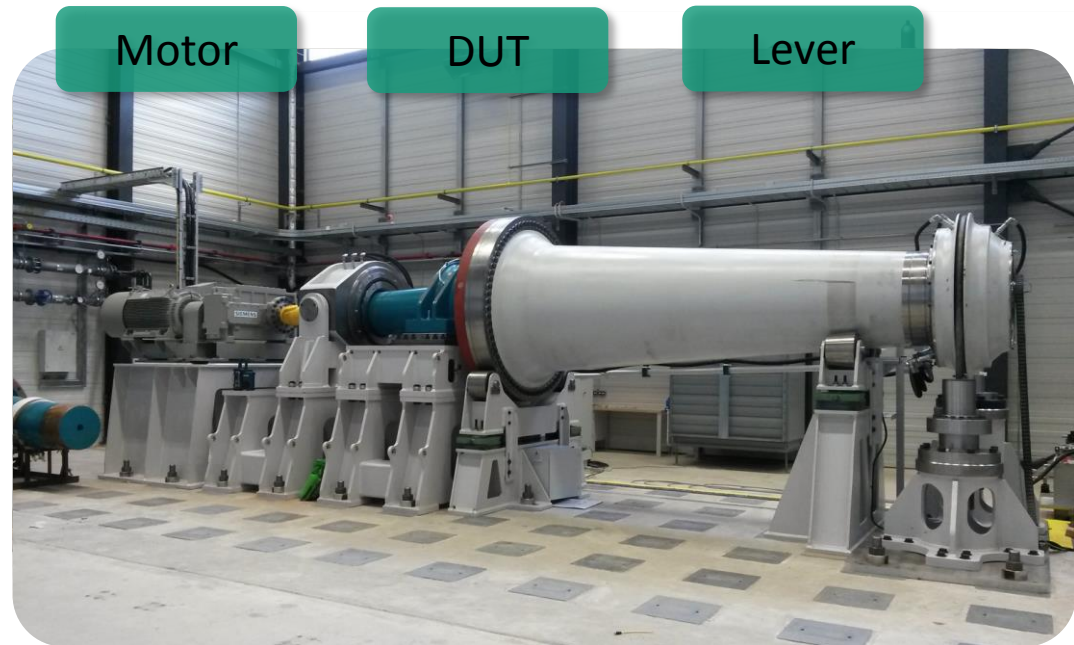
# BeBen XXL – Main shaft testing

## Key points

- Max bending moment 15 MNm
- 350 kW drive unit
- Modular adapter
- 7x15m clamping field

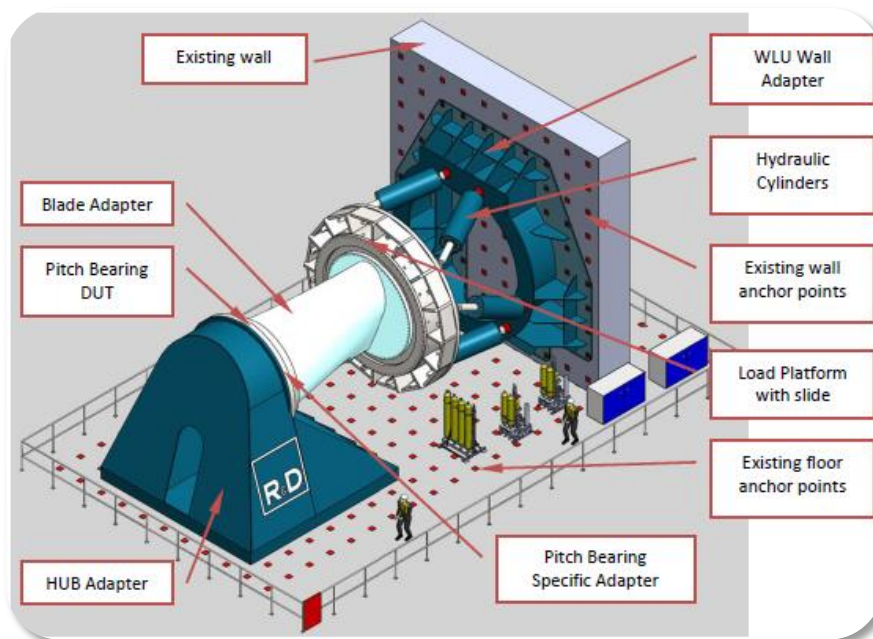
## Possible tests

- Accelerated lifetime test
- Model validation
- Functional testing



# Outline

## HAPT (**H**ighly **A**ccelerated **P**itch bearing **T**est)



### Motivation

- Currently no method for pitch bearing lifetime prediction
- Current test rigs exclude interaction with hub and blade
- Current test rigs exclude interaction with hub and blade

### Goal

- Development of suitable test rig and test method

### Capabilities

- Dynamic generation of bending moments, axial and radial forces
- Emulation of blade and hub stiffness
- Continuous pitching under load possible
- Pitch bearing diameter of 4 – 4,5 m ( ~ 10 MW turbine)
- Turbine service life in 6 month test time



# THANK YOU FOR YOUR ATTENTION



Any questions?

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BMWi Federal Ministry for Economic Affairs and Energy

BMBF Federal Ministry of Education and Research

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